Modelling High-Frequency Volatility and Liquidity Using Multiplicative Error Models

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Abstract

In this paper, we study the dynamic interdependencies between high-frequency volatility, liquidity demand as well as trading costs in an electronic limit order book market. Using data from the Australian Stock Exchange we model 1-min squared mid-quote returns, average trade sizes, number of trades and average (excess) trading costs per time interval in terms of a four-dimensional multiplicative error model. The latter is augmented to account also for zero observations. We find evidence for significant contemporaneous relationships and dynamic interdependencies between the individual variables. Liquidity is causal for future volatility but not vice versa. Furthermore, trade sizes are negatively driven by past trading intensities and trading costs. Finally, excess trading costs mainly depend on their own history.

Keywords: Multiplicative error models, volatility, liquidity, high-frequency data.

JEL Classification: C13, C32, C52

1 Introduction

Due to the permanently increasing availability of high-frequency financial data, the empirical analysis of trading behavior and the modelling of trading processes has become a major theme in modern financial econometrics. Key variables in empirical studies of high-frequency data are price volatilities, trading volume, trading intensities, bid-ask spreads and market depth as displayed by an open limit order book. A common characteristic of these variables is that they are positive-valued and persistently clustered over time.

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To capture the stochastic properties of positive-valued autoregressive processes, so-called (MEMs) have become popular. The basic idea of modelling a positive-valued process in terms of the product of positive-valued (typically i.i.d.) innovation terms and an observation-driven and/or parameter driven dynamic function is well-known in financial econometrics and originates from the model structure of the autoregressive conditional heteroscedasticity (ARCH) model introduced by Engle (1982) or the stochastic volatility (SV) model proposed by Taylor (1982). Engle and Russell (1997, 1998) introduced the autoregressive conditional duration (ACD) model to model autoregressive (financial) duration processes in terms of a multiplicative error process and a GARCH-type parameterization of the conditional duration mean. The term ‘MEM’ is ultimately introduced by Engle (2002) who discusses this approach as a general framework to model any kind of positive-valued dynamic process. Manganelli (2005) proposes a multivariate MEM to jointly model high-frequency volatilities, trading volume and trading intensities. Hautsch (2008) generalizes this approach by introducing a common latent dynamic factor serving as a subordinated process driving the individual trading components. The resulting model combines features of a GARCH type model and an SV type model and is called stochastic MEM. Engle and Gallo (2006) apply MEM specifications to jointly model different volatility indicators including absolute returns, daily range, and realized volatility. Recently, Cipollini et al. (2006) extend the MEM by a copula specification in order to capture contemporaneous relationships between the variables.

Given the growing importance of MEMs for the modelling of high-frequency trading processes, liquidity dynamics and volatility processes, this paper gives an introduction to the topic and an overview of the current literature. Given that the ACD model is the most popular specification of a univariate MEM, we will strongly rely on this string of the literature. Finally, we will present an application of the MEM to jointly model the multivariate dynamics of volatilities, trade sizes, trading intensities, and trading costs based on limit order book data from the Australian Stock Exchange (ASX).

The paper is organized as follows: Section 2 presents the major principles and properties of univariate MEMS. In Section 3 we will introduce multivariate specifications of MEMs. Estimation and statistical inference is illustrated in Section 4. Finally, Section 5 gives an application of the MEM to model high-frequency trading processes using data from the ASX.

2 The Univariate MEM

Let \( \{Y_t\}, t = 1, \ldots, T \), denote a non-negative (scalar) random variable. Then, the univariate MEM for \( Y_t \) is given by

\[
Y_t = \mu_t \varepsilon_t, \\
\varepsilon_t | F_{t-1} \sim \text{i.i.d. } D(1, \sigma^2),
\]

where \( F_t \) denotes the information set up to \( t \), \( \mu_t \) is a non-negative conditionally deterministic process given \( F_{t-1} \), and \( \varepsilon_t \) is a unit mean, i.i.d. variate process defined on
non-negative support with variance $\sigma^2$. Then, per construction we have

\[
\begin{align*}
E[Y_t|\mathcal{F}_{t-1}] &\quad \text{def} \quad \mu_t, \\
\text{Var}[Y_t|\mathcal{F}_{t-1}] &\quad = \sigma^2 \mu_t^2.
\end{align*}
\]

(1)

(2)

The major principle of the MEM is to parameterize the conditional mean $\mu_t$ in terms of a function of the information set $\mathcal{F}_{t-1}$ and parameters $\theta$. Then, the basic linear MEM($p,q$) specification is given by

\[
\mu_t = \omega + \sum_{j=1}^{p} \alpha_j Y_{t-j} + \sum_{j=1}^{q} \beta_j \mu_{t-j},
\]

(3)

where $\omega > 0$, $\alpha_j \geq 0$, $\beta_j \geq 0$. This specification corresponds to a generalized ARCH model as proposed by Bollerslev (1986) as long as $Y_t$ is the squared (de-meaned) log return between $t$ and $t-1$ with $\mu_t$ corresponding to the conditional variance. Accordingly, the process (3) can be estimated by applying GARCH software based on $\sqrt{Y_t}$ (without specifying a conditional mean function). Alternatively, if $Y_t$ corresponds to a (financial) duration, such as, e.g., the time between consecutive trades (so-called trade durations) or the time until a cumulative absolute price change is observed (so-called price durations), the model is referred to an ACD specification as introduced by Engle and Russell (1997, 1998).

The unconditional mean of $Y_t$ is straightforwardly computed as

\[
E[Y_t] = \omega / (1 - \sum_{j=1}^{p} \alpha_j - \sum_{j=1}^{q} \beta_j).
\]

(4)

The derivation of the unconditional variance is more cumbersome since it requires the computation of $E[\mu_t^2]$. In the case of an MEM(1,1) process, the unconditional variance is given by (see, e.g., Hautsch (2004))

\[
\text{Var}[Y_t] = E[Y_t^2] \sigma^2 (1 - \beta^2 - 2\alpha\beta) / (1 - (\alpha + \beta)^2 - \alpha^2 \sigma^2)
\]

(5)

corresponding to

\[
\text{Var}[Y_t] = E[Y_t^2] \sigma^2 (1 - \beta^2 - 2\alpha\beta) / (1 - \beta^2 - 2\alpha\beta - 2\alpha^2)
\]

(6)

case of $\sigma^2 = 1$ which is, e.g., associated with a standard exponential distribution. Correspondingly, the model implied autocorrelation function is given by

\[
\rho_1 \quad \text{def} \quad \text{Corr}[Y_t, Y_{t-1}] = \alpha (1 - \beta^2 - 2\alpha\beta) / (1 - \beta^2 - 2\alpha\beta),
\]

(7)

\[
\rho_j \quad \text{def} \quad \text{Corr}[Y_t, Y_{t-j}] = (\alpha + \beta) \rho_{j-1} \quad \text{for} \quad j \geq 2.
\]

(8)

Similarly to the GARCH model, the MEM can be represented in terms of an ARMA model for $Y_t$. Let $\eta_t \quad \text{def} \quad Y_t - \mu_t$ denote a martingale difference, then the MEM($p,q$) process can be written as

\[
Y_t = \omega + \sum_{j=1}^{\max(p,q)} (\alpha_j + \beta_j) Y_{t-j} - \sum_{j=1}^{q} \beta_j \eta_{t-j} + \eta_t.
\]

(9)
The weak stationarity condition of a MEM(1,1) process is given by $(\alpha + \beta)^2 - \alpha^2 \sigma^2 < 1$ ensuring the existence of $\text{Var}[Y_t]$.

Relying on the GARCH literature, the linear MEM specification can be extended in various forms. A popular form is a logarithmic specification of a MEM ensuring the positivity of $\mu_t$ without imposing parameter constraints. This is particularly important whenever the model is augmented by explanatory variables or when the model has to accommodate negative (cross-) autocorrelations in a multivariate setting. Two versions of logarithmic MEM’s have been introduced by Bauwens and Giot (2000) in the context of ACD models and are given (for simplicity for $p = q = 1$) by

$$
\log \mu_t = \omega + \alpha g(\epsilon_{t-1}) + \beta \log \mu_{t-1},
$$

where $g(\cdot)$ is given either by $g(\epsilon_{t-1}) = \epsilon_{t-1}$ (type I) or $g(\epsilon_{t-1}) = \log \epsilon_{t-1}$ (type II). The process is covariance stationary if $\beta < 1$, $E[\epsilon_t \exp\{\alpha g(\epsilon_t)\}] < \infty$ and $E[\exp\{2\alpha g(\epsilon_t)\}] < \infty$. For more details, see Bauwens and Giot (2000). Notice that due the logarithmic transformation, the news impact function, i.e., the relation between $Y_t$ and $\epsilon_{t-1}$ is not anymore linear but is convex in the type I case and is concave in the type II parameterization. I.e., in the latter case, the sensitivity of $Y_t$ to shocks in $\epsilon_{t-1}$ is higher if $\epsilon_{t-1}$ is small than in the case where it is large.

A more flexible way to capture nonlinear news responses is to allow for a kinked news response function

$$
\log \mu_t = \omega + \alpha \{|\epsilon_{t-1} - b| + c(\epsilon_{t-1} - b)\}^\delta + \beta \log \mu_{t-1},
$$

where $b$ gives the position of the kink while $\delta$ determines the shape of the piecewise function around the kink. For $\delta = 1$, the model implies a linear news response function which is kinked at $b$ resembling the EGARCH model proposed by Nelson (1991). For $\delta > 1$, the shape is convex while it is concave for $\delta < 1$. Such a specification allows to flexibly capture asymmetries in responses of $Y_t$ to small or large lagged innovation shocks, such as, e.g., shocks in liquidity demand, liquidity supply or volatility. A similar specification is considered by Cipollini et al. (2006) to capture leverage effects if $Y_t$ corresponds to a volatility variable. For more details on extended MEM specifications in the context of ACD models, see Hautsch (2004) or Bauwens and Hautsch (2008).

The error term distribution of $\epsilon_t$ is chosen as a distribution defined on positive support and standardized by its mean. If $Y_t$ is the squared (de-meaned) log return, then $\sqrt{\epsilon_t} \sim \mathcal{N}(0, 1)$ yields the Gaussian GARCH model. If $Y_t$ denotes a liquidity variable (such as trade size, trading intensity, bid-ask spread or market depth), a natural choice is an exponential distribution. Though the exponential distribution is typically too restrictive to appropriately capture the distributional properties of trading variables, it allows for a quasi maximum likelihood (QML) estimation yielding consistent estimates irrespective of distributional misspecifications. For more details, see Section 4. More flexible distributions are, e.g., the Weibull distribution, the (generalized) gamma distribution, the Burr distribution or the generalized F distribution. The latter is proposed in an ACD context by Hautsch (2003) and is given in standardized form (i.e., with unit mean) by the p.d.f.

$$
f_\epsilon(x) = [a\{x/\zeta(a, m, \eta)\}]^{a-1}[\eta + \{x/\zeta(a, m, \eta)\}]^{(-\eta-m)\eta}/\mathcal{B}(m, \eta),
$$

where $a$ is a scaling parameter, $\eta > 0$ is a shape parameter, $m > 0$ is a scale parameter, $\zeta(a, m, \eta) = \Gamma(a, m/\eta)^{-1}$ is the generalization of the gamma function to the Burr distribution, and $\mathcal{B}(m, \eta)$ is the beta function.

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where $a$, $m$, and $\eta$ are distribution parameters, $\mathcal{B}(m, \eta) = \Gamma(m) \Gamma(\eta)/\Gamma(m + \eta)$, and

\[
\zeta(a, m, \eta) \overset{\text{def}}{=} \{ \eta^{1/a} \Gamma(m + 1/a) \Gamma(\eta - 1/a) \}/\{\Gamma(m) \Gamma(\eta)\}.
\] (13)

The generalized F-distribution nests the generalized gamma distribution for $\eta \to \infty$, the Weibull distribution for $\eta \to \infty$, $m = 1$, the log-logistic distribution for $m = \eta = 1$, and the exponential distribution for $\eta \to \infty$, $m = a = 1$. For more details, see Hautsch (2004).

3 The Vector MEM

Consider in the following a $k$-dimensional positive-valued time series, denoted by $\{Y_t\}, t = 1, \ldots, T$, with $Y_t \overset{\text{def}}{=} (Y_t^{(1)}, \ldots, Y_t^{(k)})$. Then, the so-called vector MEM (VMEM) for $Y_t$ is defined by

\[
Y_t = \mu_t \circ \varepsilon_t = \text{diag}(\mu_t)\varepsilon_t,
\]

where $\circ$ denotes the Hadamard product (element-wise multiplication) and $\varepsilon_t$ is a $k$-dimensional vector of mutually and serially i.i.d. innovation processes, where the $j$-th element is given by

\[
\varepsilon_t^{(j)} | \mathcal{F}_{t-1} \sim \text{i.i.d. } \mathcal{D}(1, \sigma_j^2), \quad j = 1, \ldots, k.
\]

A straightforward extension of the univariate linear MEM as proposed by Manganelli (2005) is given by

\[
\mu_t = \omega + \mathcal{A}_0 Y_t + \sum_{j=1}^p \mathcal{A}_j Y_{t-j} + \sum_{j=1}^q \mathcal{B}_j \mu_{t-j},
\] (14)

where $\omega$ is a $(k \times 1)$ vector, and $\mathcal{A}_0$, $\mathcal{A}_j$, and $\mathcal{B}_j$ are $(k \times k)$ parameter matrices. The matrix $\mathcal{A}_0$ captures contemporaneous relationships between the elements of $Y_t$ and is specified as a matrix where only the upper triangular elements are non-zero. This triangular structure implies that $Y_t^{(i)}$ is predetermined for all variables $Y_t^{(j)}$ with $j < i$. Consequently, $Y_t^{(i)}$ is conditionally i.i.d. given $\{Y_t^{(j)}, \mathcal{F}_{t-1}\}$ for $j < i$.

The advantage of this specification is that contemporaneous relationships between the variables are taken into account without requiring multivariate distributions for $\varepsilon_t$. This eases the estimation of the model. Furthermore, the theoretical properties of univariate MEMs as discussed in the previous section can be straightforwardly extended to the multivariate case. However, an obvious drawback is the requirement to impose an explicit ordering of the variables in $Y_t$ which is typically chosen in accordance with a specific research objective or following economic reasoning. An alternative way to capture contemporaneous relationships between the elements of $Y_t$ is to allow for mutual correlations between the innovation terms $\varepsilon_t^{(j)}$. Then, the innovation term vector follows a density function which is defined over non-negative $k$-dimensional support $[0, +\infty)^k$ with unit mean $1$ and covariance matrix $\Sigma$, i.e.,

\[
\varepsilon_t | \mathcal{F}_{t-1} \sim \text{i.i.d. } \mathcal{D}(1, \Sigma)
\]


implying

\[ \begin{align*} 
E[Y_t | \mathcal{F}_{t-1}] &= \mu_t, \\
\text{Var}[Y_t | \mathcal{F}_{t-1}] &= \mu_t \mu_t^\top \otimes \Sigma = \text{diag}(\mu_t) \Sigma \text{ diag}(\mu_t).
\end{align*} \]

Finding an appropriate multivariate distribution defined on positive support is a difficult task. As discussed by Cipollini et al. (2006), a possible candidate is a multivariate gamma distribution which however imposes severe restrictions on the contemporaneous correlations between the errors \( \epsilon_i \). Alternatively, copula approaches can be used as, e.g., proposed by Heinen and Rengifo (2006) or Cipollini et al. (2006).

In correspondence to the univariate logarithmic MEM, we obtain a logarithmic VMEM specification by

\[ \log \mu_t = \omega + \mathcal{A}_0 \log Y_t + \sum_{j=1}^p \mathcal{A}_j g(\epsilon_{t-j}) + \sum_{j=1}^q \mathcal{B}_j \log \mu_{t-j}, \] (15)

where \( g(\epsilon_{t-j}) = \epsilon_{t-j} \) or \( g(\epsilon_{t-j}) = \log \epsilon_{t-j} \), respectively. Generalized VMEMs can be specified accordingly to Section 2.

A further generalization of VMEM processes has been introduced by Hautsch (2008) and captures mutual (time-varying) dependencies by a subordinated common (latent) factor jointly driving the individual processes. The so-called stochastic MEM can be compactly represented as

\[ Y_t = \mu_t \odot \lambda_t \odot \epsilon_t, \] (16)

where \( \lambda_t \) is a \((k \times 1)\) vector with elements \( \{\lambda_{t}^k\} \), \( i = 1, \ldots, k \),

\[ \log \lambda_t = a \log \lambda_{t-1} + \nu_t \quad \nu_t \sim \text{i.i.d. } \mathcal{N}(0, 1), \] (17)

and \( \nu_t \) is assumed to be independent of \( \epsilon_t \). Hence, \( \lambda_t \) serves as a common dynamic factor with process-specific impacts \( \delta_i \). Then, the elements of \( \mu_t \) represent ’genuine’ (trade-driven) effects given the latent factor. They are assumed to follow (15) with \( g(\epsilon_t) = Y_t \odot \mu_{t-1}^{-1} \). The model corresponds to a mixture model and nests important special cases, such as the SV model by Taylor (1982) or the stochastic conditional duration model by Bauwens and Veredas (2004). Applying this approach to jointly model high-frequency volatilities, trade sizes and trading intensities, Hautsch (2008) shows that the latent component is a major driving force of cross-dependencies between the individual processes.

4 Statistical Inference

Define \( f(Y_t^{(1)}, Y_t^{(2)}, \ldots, Y_t^{(k)} | \mathcal{F}_{t-1}) \) as the joint conditional density given \( \mathcal{F}_{t-1} \). Without loss of generality the joint density can be decomposed into

\[ f(Y_t^{(1)}, Y_t^{(2)}, \ldots, Y_t^{(k)} | \mathcal{F}_{t-1}) = f(Y_t^{(1)} | Y_t^{(2)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1}) \]
\[ \times f(Y_t^{(2)} | Y_t^{(3)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1}) \]
\[ \times f(Y_t^{(k)} | \mathcal{F}_{t-1}). \] (18)
Then, the log likelihood function is defined by
\[
\mathcal{L}(\theta) \overset{\text{def}}{=} \sum_{t=1}^{T} \sum_{j=1}^{k} \log f(Y_t^{(j)} | Y_t^{(j+1)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1}).
\] (21)

For instance, if \( Y_t^{(j)} | Y_t^{(j+1)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1} \) follows a generalized F distribution with parameters \( a^{(j)}, m^{(j)} \) and \( \eta^{(j)} \), the corresponding log likelihood contribution is given by
\[
\log f(Y_t^{(j)} | Y_t^{(j+1)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1})
= \log \left[ \Gamma(m^{(j)} + \eta^{(j)}) / \{ \Gamma(m^{(j)}) \Gamma(\eta^{(j)}) \} \right] + \log a^{(j)} - a^{(j)} m^{(j)} \log \hat{\mu}_t^{(j)}
+ (a^{(j)} m^{(j)} - 1) \log Y_t^{(j)} - (\eta^{(j)} + m^{(j)}) \log \left( \eta^{(j)} + Y_t^{(j)} / \hat{\mu}_t^{(j)} \right)
+ \eta^{(j)} \log(\eta^{(j)}),
\] (22)

where \( \hat{\mu}_t^{(j)} = \mu_t^{(j)} / \zeta(a^{(j)}, m^{(j)}, \eta^{(j)}) \) and \( \zeta(\cdot) \) defined as above.

Constructing the likelihood based on an exponential distribution leads to the quasi likelihood function with components
\[
\log f(Y_t^{(j)} | Y_t^{(j+1)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1}) = - \sum_{t=1}^{T} \left( \log \mu_t^{(j)} + Y_t^{(j)} / \mu_t^{(j)} \right),
\]
where the score and Hessian are given by
\[
\frac{\partial \log f(Y_t^{(j)} | Y_t^{(j+1)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1})}{\partial \theta^{(j)}} = - \sum_{t=1}^{T} \frac{\partial \mu_t^{(j)}}{\partial \theta^{(j)}} \left( \frac{Y_t^{(j)}}{\mu_t^{(j)}} - 1 \right),
\]
\[
\frac{\partial^2 \log f(Y_t^{(j)} | Y_t^{(j+1)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1})}{\partial \theta^{(j)} \partial \theta^{(j)}} = \sum_{t=1}^{T} \left\{ \frac{\partial}{\partial \theta^{(j)}} \left( \frac{1}{\mu_t^{(j)}} \frac{\partial \mu_t^{(j)}}{\partial \theta^{(j)}} \right) \left( \frac{Y_t^{(j)}}{\mu_t^{(j)}} - 1 \right) - \frac{1}{\mu_t^{(j)}} \frac{\partial \mu_t^{(j)}}{\partial \theta^{(j)}} \frac{\partial \mu_t^{(j)}}{\partial \theta^{(j)}} \frac{Y_t^{(j)}}{\mu_t^{(j)}} \right\}.
\]


Model evaluation can be straightforwardly performed by testing the dynamic and distributional properties of the model residuals
\[
e_t^{(j)} \overset{\text{def}}{=} \hat{e}_t^{(j)} = Y_t^{(j)} / \hat{\mu}_t^{(j)}.
\] (26)

Under correct model specification, the series \( e_t^{(j)} \) must be i.i.d. with distribution \( \mathbb{D}(\cdot) \). Portmanteau statistics such as the Ljung-Box statistic (Ljung and Box 1978) based on (de-meaned) MEM residuals can be used to analyze whether the specification is able to capture the dynamic properties of the process. The distributional properties
can be checked based on QQ-plots. Engle and Russell (1998) propose a simple test for no excess dispersion implied by an exponential distribution using the statistic
\[
\sqrt{n} \left\{ \left( \hat{\sigma}^2_{e(j)} - 1 \right) / \tilde{\sigma}^{(j)} \right\},
\]
where \( \hat{\sigma}^2_{e(j)} \) is the sample variance of \( e_{i(j)} \) and \( \tilde{\sigma}^{(j)} \) is the standard deviation of \( (e_{i(j)} - 1)^2 \). Under the null hypothesis of an exponential distribution, the test statistic is asymptotically normally distributed with \( \hat{\sigma}^2_{e(j)} = 1 \) and \( (\tilde{\sigma}^{(j)})^2 = \sqrt{8} \).

Alternatively, probability integral transforms can be used to evaluate the in-sample goodness-of-fit, see, e.g., Bauwens et al. (2004). Building on the work by Rosenblatt (1952), Diebold et al. (1998) show that
\[
q_t^{(j)} \overset{\text{def}}{=} \int_{-\infty}^{\infty} f_{e_{i(j)}}(s) ds
\]
must be i.i.d. \( U[0,1] \). Alternative ways to evaluate MEMs are Lagrange Multiplier tests as proposed by Meitz and Teräsvirta (2006), (integrated) conditional moment tests as discussed by Hautsch (2006) or nonparametric tests as suggested by Fernandes and Grammig (2006).

5 High-Frequency Volatility and Liquidity Dynamics

In this section, we will illustrate an application of the VMEM to jointly model return volatilities, average trade sizes, the number of trades as well as average trading costs in intra-day trading. We use a data base extracted from the electronic trading of the Australian Stock Exchange (ASX) which is also used by Hall and Hautsch (2006, 2007). The ASX is a continuous double auction electronic market where the continuous trading period between 10:09 a.m. and 4:00 p.m. is preceded and followed by a call auction. During continuous trading, any buy (sell) order entered that has a price that is greater than (less than) or equal to existing queued buy (sell) orders, will execute immediately and will result in a transaction as long as there is no more buy (sell) order volume that has a price that is equal to or greater (less) than the entered buy (sell) order. In case of partial execution, the remaining volume enters the limit order queues. Limit orders are queued in the buy and sell queues according to a strict price-time priority order and may be entered, deleted and modified without restriction. For more details on ASX trading, see Hall and Hautsch (2007).

Here, we use data from completely reconstructed order books for the stocks of the National Australian Bank (NAB) and BHP Billiton Limited (BHP) during the trading period July and August 2002 covering 45 trading days. In order to reduce the impact of opening and closure effects, we delete all observations before 10:15 a.m. and after 3:45 p.m. To reduce the complexity of the model we restrict our analysis to equidistant observations based on one-minute aggregates. For applications of MEMs to irregularly spaced data, see Manganelli (2005) or Engle (2000).

Table 1 shows summary statistics for log returns, the average trade size, the number of trades, and the average (time-weighted) trading costs. The log returns correspond to the residuals of an MA(1) model for differences in log transaction prices. This pre-adjustment removes the effects of the well-known bid-ask bounce causing negative
first-order serial correlation, see Roll (1984). The trading costs are computed as the hypothetical trading costs of an order of the size of 10,000 shares in excess to the trading costs which would prevail if investors could trade at the mid-quote. They are computed as a time-weighted average based on the average ask and bid volume pending in the queues and yield natural measures of transaction costs induced by a potentially lacking liquidity supply. Conversely, trade sizes and the number of trades per interval indicate the liquidity demand in the market.

We observe that high-frequency log returns reveal similar stochastic properties as daily log returns with significant overkurtosis and slight left-skewness. For the average trade size and the number of trades per interval we find a highly right-skewed distribution with a substantial proportion of observations being zero. These observations stem from tranquil trading periods, where market orders do not necessarily occur every minute. As illustrated below, these periods typically happen around noon causing the well-known ‘lunch-time dip’. On the other hand, we also find evidence for very active trading periods resulting in a high speed of trading and large average trade sizes. On average, the number of trades per one-minute interval is around 2.5 and 3.5 for NAB and BHP, respectively, with average trade sizes of approximately 2,300 and 5,800 shares, respectively. The excess trading costs associated with the buy/sell transaction of 10,000 shares are on average around 60 ASD for BHP and 188 ASD for NAB. Hence, on average, excess trading costs for NAB are significantly higher than for BHP which is caused by a higher average bid-ask spread and a lower liquidity supply in the book. The Ljung-Box statistics indicate the presence of a strong serial dependence in volatilities and all liquidity variables, and thus reveal the well-known clustering structures in trading processes. The significant Ljung-Box statistics for log returns are induced by the bid-ask bounce effect causing significantly negative first-order autocorrelation. Obviously, the MA(1) filter does not work very well in the case of NAB data. Alternatively, one could use higher order MA-filter. The empirical autocorrelations (ACFs) shown in Figure 1 confirm a relatively high persistence in volatilities and liquidity variables indicated by the Ljung-Box statistics. A notable exception is the process of trade sizes for NAB revealing only weak serial dependencies. Figure 2 displays the cross-autocorrelation functions (CACFs) between the individual variables. It turns out that squared returns are significantly positively (cross-)autocorrelated with the number of trades and excess trading costs, and – to less extent – with the average trade size. This indicates strong dynamic interdependencies between volatility and liquidity demand as well as supply. Similarly, we also observe significantly positive CACFs between trade sizes and the speed of trading. Hence, periods of high liquidity demand are characterized by both high trade sizes and a high trading intensity. Conversely, the CACFS between trading costs and trade sizes as well as between trading costs and the trading intensity are significantly negative. Ceteris paribus this indicates that market participants tend to exploit periods of high liquidity supply, i.e. they trade fast and high volumes if the trading costs are low and thus liquidity supply is high.

Figure 1: Sample ACF of squared log returns (SR), trade size (TS), number of trades (NT), and trade costs (TC)(from top to bottom) for BHP (left) and NAB (right). The x-axis shows the lags. The broken line shows the asymptotic 95% confidence intervals.

A typical feature of high-frequency data is the strong influence of intra-day sea-
Table 1: Descriptive statistics of log returns (LR), trade sizes (TS), number of trades (NT), and trade costs (TC) for BHP and NAB. Evaluated statistics: mean value, standard deviation (S.D.), minimum and maximum, 10%- and 90%-quantile (q10 and q90, respectively), kurtosis, and the Ljung-Box statistic (associated with 20 lags). LB$_{20}$(SR) represents the Ljung-Box statistic computed for the squared log returns (SR).

Figure 2: Sample CACF for BHP (top) and NAB (bottom). The solid, dash-dotted and dashed lines show the CACF between TC and SR, TC and TS, TC and NT, respectively, on the left side and between SR and TS, SR and NT, TS and NT, respectively, on the right side. The dotted line shows the asymptotic 95% confidence interval. The x-axis shows the lags.

Conceptual difficulties are caused by the relatively high number of zeros in the liquidity demand variables which cannot be captured by a standard MEM requiring...
positive random variables. In order to account for zeros, we augment a Log-VMEM
by corresponding dummy variables:

$$
\log \mu_t = \omega + A \varepsilon_t \circ \mathbf{1}_{\{Y_t > 0\}} + A_0 \circ \mathbf{1}_{\{Y_t = 0\}}
$$  \hfill (27)

$$
+ \sum_{j=1}^{p} A_j [g(\varepsilon_{t-j}) \circ \mathbf{1}_{\{Y_{t-j} > 0\}}] + \sum_{j=1}^{p} A_0 \circ \mathbf{1}_{\{Y_{t-j} = 0\}}
$$  \hfill (28)

$$
+ \sum_{j=1}^{q} B_j \log \mu_{t-j},
$$  \hfill (29)

where $\mathbf{1}_{\{Y_t > 0\}}$ and $\mathbf{1}_{Y_t = 0}$ denote $k \times 1$ vectors of indicator variables indicating non-zero and zero realizations, respectively, and $A_j, j = 0, \ldots, p$, are corresponding $k \times k$ parameter matrices.

Then, the log likelihood function is split up into two parts yielding

$$
\mathcal{L}(\theta) = \sum_{t=1}^{T} \sum_{j=1}^{k} \log f(Y_t^{(j)} | Y_t^{(j+1)}, \ldots, Y_t^{(k)}; Y_{t-j} > 0, \mathcal{F}_{t-1})
$$  \hfill (30)

$$
\times \log P(Y_t^{(j)} > 0 | Y_t^{(j+1)}, \ldots, Y_t^{(k)}; \mathcal{F}_{t-1}).
$$  \hfill (31)

If both likelihood components have no common parameters, the second part can be
maximized separately based on a binary choice model including past (and contemporaneous) variables as regressors. Then, the first log likelihood component is associated
only with positive values and corresponds to the log likelihood given by (27).

We estimate a four-dimensional Log-VMEM for squared log returns, trade sizes,
the number of trades and transaction costs standardized by their corresponding season-
ality components. For simplicity and to keep the model tractable, we restrict our analy-
sis to a specification of the order $p = q = 1$. The innovation terms are chosen as $g(\varepsilon_t) = \varepsilon_t$. For the process of squared returns, $Y_t^{(1)} = r_t^2$, we assume
$Y_t^{(1)} | Y_t^{(2)}, \ldots, Y_t^{(k)}, \mathcal{F}_{t-1} \sim \mathcal{N}(0, \mu_t^{(1)})$. Accordingly, for $Y_t^{(j)}, j \in \{2, 3, 4\}$, we assume $Y_t^{(j)} | Y_t^{(j+1)}, \ldots, Y_t^{(4)}, \mathcal{F}_{t-1} \sim \mathcal{E}(\mu_t^{(j)})$. Though it is well-known that both the normal and the exponential distribution are not flexible enough to capture the distributional properties of high-frequency trading processes, they allow for a QML estimation of the model.

Hence, the adjustments for zero variables have to be done only in the liquidity components but not in the return component. Moreover, note that there are no zeros in the trading cost component. Furthermore, zero variables in the trade size and the number of trades per construction always occur simultaneously. Consequently, we can only identify the $(2,3)$-element in $A_0$ and one of the two middle columns in $A_1$, where all other parameters in $A_0$ and $A_1$ are set to zero.

For the sake of brevity we do not show the estimation results of the binary choice component but restrict our analysis to the estimation of the MEM. Figure 2 shows the estimation results for BHP and NAB based on a specification with fully parameterized matrix $A_1$ and diagonal matrix $B_1$. 

Figure 3: Deterministic intra-day seasonality patterns for SR, TS, NT and TC (from top to bottom) for BHP (left) and NAB (right). The seasonality components are estimated using cubic spline functions based on 30-minute nodes. The x-axis gives the time of the day.
Table 2: Quasi-maximum likelihood estimation results of a MEM for seasonally adjusted (i) squared (bid-ask bounce adjusted) log returns, (ii) average trade sizes, (iii) number of trades, and (iv) average trading costs per one-minute interval. Standard errors are computed based on the OPG covariance matrix.
Descriptive statistics of seasonally adjusted data

<table>
<thead>
<tr>
<th></th>
<th>BHP</th>
<th>NAB</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mean</td>
<td>1.000</td>
<td>1.001</td>
</tr>
<tr>
<td>S.D.</td>
<td>1.963</td>
<td>1.528</td>
</tr>
<tr>
<td>LB_{20}</td>
<td>1159.456</td>
<td>202.001</td>
</tr>
</tbody>
</table>

Descriptive statistics of MEM-residuals

<table>
<thead>
<tr>
<th></th>
<th>BHP</th>
<th>NAB</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mean</td>
<td>1.000</td>
<td>1.000</td>
</tr>
<tr>
<td>S.D.</td>
<td>1.568</td>
<td>1.348</td>
</tr>
<tr>
<td>LB_{20}</td>
<td>63.559</td>
<td>61.388</td>
</tr>
</tbody>
</table>

Table 3: Summary statistics of the seasonality adjusted time series and the corresponding MEM residuals for BHP and NAB.

We can summarize the following major findings: First, we observe significant mutual correlations between nearly all variables. Confirming the descriptive statistics above, volatility is positively correlated with liquidity demand and liquidity supply. Hence, active trading as driven by high volumes and high trading intensities is accompanied by high volatility. Simultaneously, as indicated by significantly negative estimates of \( A_{24} \) and \( A_{34} \), these are trading periods which are characterized by low transaction costs.

Second, as indicated by the diagonal elements in \( A_1 \) and the elements in \( B_1 \), all trading components are strongly positively autocorrelated but are not very persistent. As also revealed by the descriptive statistics, the strongest first order serial dependence is observed for the process of trading costs. The persistence is highest for trade sizes and trading intensities.

Third, we find Granger causalities from liquidity variables to future volatility. High trade sizes predict high future return volatilities. However, the impact of trading intensities and trading costs on future volatility is less clear. Here, we find contradictory results for both stocks. Conversely, we do not observe any predictability of return volatility for future liquidity demand and supply. For both stocks all corresponding coefficients are insignificant.

Fourth, trade sizes are significantly negatively driven by past trading intensities and past trading costs. This finding indicates that a high speed of trading tends to reduce trade sizes over time. Similarly, increasing trading costs deplete the incentive for high order sizes but on the other hand increase the speed of trading. Hence, market participants observing a low liquidity supply reduce trade sizes but trade more often. A possible explanation for this finding is that investors tend to break up large orders into sequences of small orders.

Fifth, (excess) transaction costs depend only on their own history but not on the lagged volatility or liquidity demand. This indicates that liquidity supply is difficult to predict based on the history of the trading process.

Sixth, as shown by the summary statistics of the MEM residuals, the model captures a substantial part of the serial dependence in the data. This is indicated by a sig-
significant reduction of the corresponding Ljung-Box statistics. Nevertheless, for some processes, there is still significant remaining serial dependence in the residuals. This is particularly true for the trading cost and trading intensity components for which obviously higher order dynamics have to be taken into account. For the sake of brevity we refrain from showing results of higher parameterized models. Allowing for more dynamic and distributional flexibility further improves the goodness-of-fit, however, makes the model less tractable and less stable for out-of-sample forecasts.

6 Conclusion

In summary, we find strong dynamic interdependencies and causalities between high-frequency volatility, liquidity demand, and liquidity supply. In particular, the high trade sizes are able to predict high future volatilities whereas the return volatility appears not to give rise to future liquidity demand and supply dynamic. The effects of the trading intensities and trading costs on future volatilities could not be uniformly concluded although these effects seem to be significant. An interesting finding is that the high trade costs, associated with low liquidity supply, lead to a decrease of the trade sizes and simultaneously to an increase of the trade intensities. However, the dynamic of the trade costs seems to be mostly driven by its own history. Last but not at least we find a higher persistence by liquidity variables than by return volatilities. Hence, these results might serve as valuable input for trading strategies and (automated) trading algorithms.

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